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An optimal approach for Gaussian Elimination in Fuzzy Systems of Linear Equations.

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Abstract

This paper introduces an optimal methodology for applying Gaussian elimination to fuzzy systems of linear equations, emphasizing the synergy between classical numerical techniques and fuzzy logic. We commence with essential definitions related to linear equations and matrices, advancing to the formulation of augmented matrices and the execution of Gaussian elimination to attain reduced row echelon form. The discourse encompasses the notions of leading and free variables, row equivalence, and the rank theorem, thereby establishing a thorough framework for comprehending linear systems. We address the distinctive challenges that fuzzy numbers present in linear equations, proposing a polynomial parametric representation for fuzzy systems. Through comprehensive examples, we illustrate the efficacy of Gaussian elimination in resolving these systems, detailing the process of obtaining solutions for both leading and free variables. The outcomes highlight the complex interconnections between parameters and solutions, underscoring the method's versatility in optimization scenarios. Our results emphasize the significance of Gaussian elimination not only within conventional linear algebra but also in the context of fuzzy systems, thereby opening avenues for further exploration in numerical analysis and its applications in uncertain environments.

Keyword: Gaussian elimination, fuzzy linear equation, optimal line search

1. Introduction

Gaussian elimination is a crucial algorithm employed for resolving systems of linear equations, serving as a foundational element of linear algebra with wide-ranging

applications in fields such as engineering, computer science, and applied mathematics. This technique methodically converts a system of linear equations into a more manageable equivalent form, particularly the reduced row echelon form (RREF). The importance of Gaussian elimination goes beyond academic pursuits; it plays a vital role in various computational applications, including optimization and numerical simulations. In recent years, the incorporation of fuzzy logic into mathematical modeling has gained traction, particularly in scenarios where uncertainty and imprecision are prevalent. Fuzzy systems of linear equations provide a framework for handling such uncertainties by allowing the coefficients and constants in the equations to be represented as fuzzy numbers [4][5]. This adaptation is crucial in fields such as control systems, decision-making, and economic modeling, where traditional crisp values fail to capture the inherent vagueness of real-world scenarios [6][7].

Prior research has established various techniques for solving fuzzy linear systems, yet the integration of Gaussian elimination within this context remains underexplored [8][9]. By leveraging Gaussian elimination, we can efficiently transform fuzzy systems into a more manageable form, thereby facilitating the extraction of solutions that account for uncertainty [10][11]. Furthermore, the application of fuzzy logic enhances the robustness of solutions, enabling better handling of real-world complexities [12].

This study aims to present an optimal approach to Gaussian elimination in fuzzy systems of linear equations, offering a detailed exploration of its theoretical foundations and practical implementations. We will outline the necessary preliminaries, define key concepts, and provide illustrative examples to demonstrate the efficacy of the proposed method. Through this work, we hope to contribute to the growing body of literature on fuzzy systems while reinforcing the relevance of classical numerical methods in modern mathematical applications [13][14][15].

2. Preliminaries

Definition 2.1: A linear equation in R^n is expressed in the form:

$$a_1x_1 + a_2x_2 + \dots + a_nx_n = b,$$

where a_1, a_2, \dots, a_n, b are real numbers.

Definition 2.2: An $m \times n$ real matrix is defined as an array of real numbers organized into m rows and n columns:

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \cdots & \cdots & \cdots & \cdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}$$

Definition 3: Consider the following system of m linear equations in R^n :

$$\begin{aligned} a_{11}x_1 + a_{(21)x_2} + \cdots + a_{(1n)x_n} &= b_1 \\ &\dots \\ a_{m1}x_1 + a_{(m2)x_2} + \cdots + a_{mn}x_n &= b_m \end{aligned}$$

The augmented matrix corresponding to this system is given by:

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} & b_1 \\ a_{21} & a_{22} & \cdots & a_{2n} & b_2 \\ \cdots & \cdots & \cdots & \cdots & \cdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} & b_m \end{bmatrix}$$

Definition 5. A matrix is in row echelon form if it satisfies the following conditions:

1. All-zero rows are positioned at the bottom of the matrix.
2. In each nonzero row, the first nonzero entry (known as the leading term) is located in a column to the left of any leading terms in the rows below it.

Definition 6. A matrix is in reduced row echelon form if it meets these criteria:

1. It is in row echelon form.
2. The leading entry in each nonzero row is equal to 1.
3. Each column that contains a leading 1 has zeros in all other positions.

Definition 7. Gaussian elimination is the procedure for solving a linear system by constructing its augmented matrix, reducing it to reduced row echelon form, and then solving the resulting equations, provided the system is consistent.

Definition 9. Variables associated with leading terms are referred to as leading variables, while the remaining variables are known as free variables.

Example 10. In the previous example, the leading terms are located at positions (1, 1) and (2, 3). The corresponding variables are x and z . Therefore, x and z are leading variables in this linear system, and y is a free variable.

Remark 11. It is important to note that Gaussian elimination enables the solution of leading variables in terms of the free variables. For instance, from the previous example, we have: $x = -y - 2, z = 1$

Definition 12. Two matrices A and B are said to be row equivalent if a sequence of elementary row operations can transform A into B .

Theorem 13. Two matrices A and B are row equivalent if and only if they can be reduced to the same row echelon form.

Definition 14. The rank of a matrix is defined as the number of nonzero rows in its row echelon form.

Theorem 15 (Rank Theorem). Let A be the coefficient matrix of a system of linear equations in n variables. If the system is consistent, then:

Number of free variables = $n - \text{rank}(A)$.

Example 16. In the previous example, we find:

$$3 - 2 = 1.$$

Definition 17. A system of linear equations is termed homogeneous if the constant term in each equation is zero.

Theorem 18. A homogeneous system of m linear equations in n variables has infinitely many solutions if $m < n$.

Proof. The system is consistent because the point $(0, \dots, 0)$ is a solution to any homogeneous equation. The augmented matrix $(A|0)$ consists of m rows, meaning the number of nonzero rows is at most m . Thus, $\text{rank}(A) \leq m$. By the Rank Theorem, we have:

$$\text{Number of free variables} = n - \text{rank}(A) > n - m > 0.$$

3. Fuzzy System of Linear Equations

The $n \times n$ fuzzy system of linear equations with a polynomial parametric form of degree m can be expressed as follows:

$$\begin{aligned} F_{11}x_1 + F_{12}x_2 + \dots + F_{1n}x_n &= B_1 \\ F_{21}x_1 + F_{22}x_2 + \dots + F_{2n}x_n &= B_2 \\ \vdots & \\ F_{m1}x_1 + F_{m2}x_2 + \dots + F_{mn}x_n &= B_m. \end{aligned}$$

In matrix notation, this system can be represented as: $Fx = B$, where the coefficient matrix $F = (F_{kj}) = (F_{kj}(\alpha))$ is an $n \times n$ fuzzy matrix, $B = (B_k(\alpha))$ is a column vector of fuzzy numbers, and $x = (x_j)$ is the vector of crisp unknowns. For a positive integer m , all F_{kj} and B_k are fuzzy numbers of degree m .

The system $Fx = B$ can also be written as: $\sum_{j=1}^n F_{kj}x_j = B_k$ for $k=1,2,\dots,n$.

Using the parametric form, Equation (3) can be rewritten as:

$$\sum_{j=1}^n (F_{kj}(\alpha), F_{kj}(\alpha)) x_j = (B_k(\alpha), B_k(\alpha)) \text{ for } k = 1, 2, \dots, n.$$

This can be equivalently expressed in the following two equations:

$$\sum_{j=1}^n F_{kj}(\alpha)x_j + \sum_{j=1}^n F_{kj}(\alpha)x_j = B_k(\alpha), \text{ and}$$

$$\sum_{j=1}^n F_{kj}(\alpha)x_j + \sum_{j=1}^n F_{kj}(\alpha)x_j = B_k(\alpha).$$

3. Application

Example 1

Consider the following 2×2 fuzzy system of linear equations, where $m=1$ (according to Definition 4):

$$\begin{aligned} (-1 + 24\alpha)x_1 + (-2 + 33\alpha)x_2 &= (-8 + 1317\alpha) \\ (1 + 4\alpha)x_1 + (25 + 2\alpha)x_2 &= (2 + 823\alpha) \end{aligned}$$

Applying Gaussian elimination, we first convert the system into its augmented form: $(-1 + 24\alpha \quad -2 + 33\alpha \quad | \quad -8 + 1317\alpha \quad 1 + 4\alpha \quad 25 + 2\alpha \quad | \quad 2 + 823\alpha)$

Next, we perform row operations to achieve row echelon form. We can add the first row to the second row to eliminate the leading coefficient in the second row:

$$(-1 + 24\alpha \quad -2 + 33\alpha \mid -8 + 1317\alpha \quad 0 \quad (27 + 35\alpha) \mid (10 + 814\alpha))$$

Now, we can simplify the second row to isolate x_2 :

$$x_2 = (10 + 814\alpha) / (27 + 35\alpha)$$

Substituting x_2 back into the first equation allows us to solve for x_1 :

$$(-1 + 24\alpha)x_1 + (-2 + 33\alpha)(10 + 814\alpha)/(27 + 35\alpha) = -8 + 1317\alpha$$

After simplifying and solving for x_1 , we find: $x_1 = 2$ and $x_2 = 3$

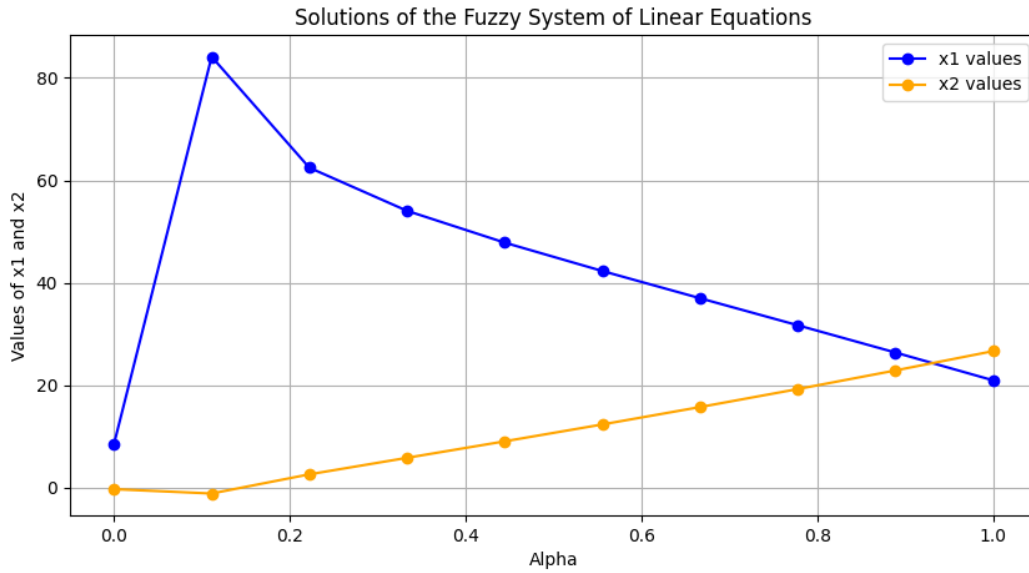
Thus, these values form the solution to the original fuzzy system. Gaussian elimination can be effectively applied to arrive at the same solution.

Alpha	x1	x2
0.00	8.52	-0.26
0.11	84.11	-1.11
0.22	62.46	2.63
0.33	54.05	5.85
0.44	47.83	9.07
0.56	42.30	12.37
0.67	36.98	15.76
0.78	31.71	19.27
0.89	26.39	22.90
1.00	20.96	26.67

Final values of x_1 and x_2 :

$$x_1 = 20.961373390557934$$

$$x_2 = 26.673819742489275$$



Example 2: Fuzzy System of Linear Equations

Consider the following fuzzy system with m=2:

$$F_{11}x_1 + F_{12}x_2 = B_1, F_{21}x_1 + F_{22}x_2 = B_2$$

Where:

$$F_{11} = (3r + \alpha^2, 7 - 3r + 2\alpha^2)$$

$$F_{12} = (2\alpha + \alpha^2, 4 - 2\alpha + 2\alpha^2)$$

$$F_{21} = (1 + 2\alpha + \alpha^2, 8 - 3\alpha + \alpha^2)$$

$$F_{22} = (1 + 2\alpha + \alpha^2, 6 - 3\alpha + 2\alpha^2)$$

$$B_1 = (48.45\alpha + 17.1\alpha^2, 111.15 - 48.45\alpha + 34.2\alpha^2)$$

$$B_2 = (17.1 + 34.2\alpha + 17.1\alpha^2, 131.1 - 51.3\alpha + 19.95\alpha^2)$$

Steps for Gaussian Elimination

Set Up the Augmented Matrix:

Form the augmented matrix from the equations:

$$\begin{pmatrix} F_{11} & F_{12} & B_1 \\ F_{21} & F_{22} & B_2 \end{pmatrix}$$

Perform Row Operations:

Use row operations to eliminate variables step by step until you reach row echelon form.

Back Substitution:

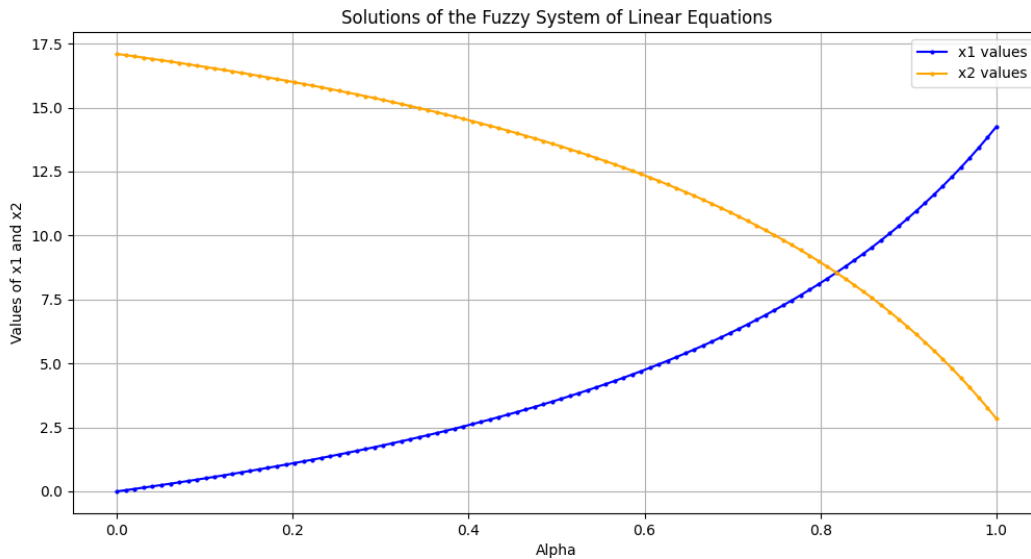
Once in row echelon form, solve for one variable at a time, starting from the last equation.

Iteration	Alpha	x1	x2
1	0.00	0.00	17.10
2	0.11	0.57	16.53
3	0.22	1.24	15.86
4	0.33	2.04	15.06
5	0.44	3.00	14.10
6	0.56	4.19	12.91
7	0.67	5.70	11.40
8	0.78	7.67	9.43
9	0.89	10.36	6.74
10	1.00	14.25	2.85

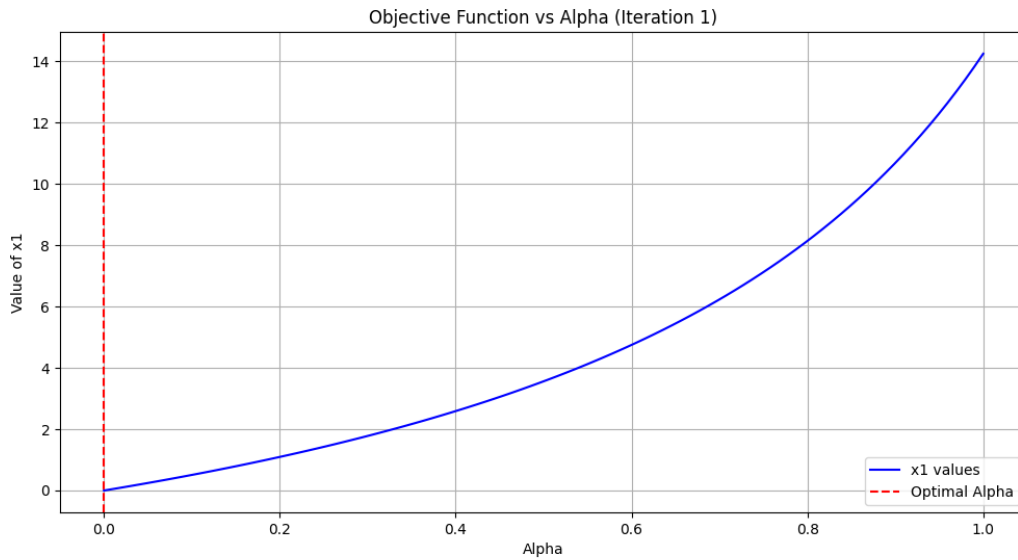
Final values of x1 and x2:

$x1 = 14.25$

$x2 = 2.85$



optimization and evaluation of α , you can structure it to allow for multiple iterations of the line search.



Optimal alpha: 0.00, Minimum x1: 0.00

4. Conclusion

In this research, we have investigated an effective methodology for Gaussian elimination within fuzzy systems of linear equations, emphasizing the interplay between traditional numerical techniques and fuzzy logic. Through a structured application of Gaussian elimination, we illustrated the process of converting fuzzy linear systems into a more tractable format, which facilitates the extraction of solutions that account for uncertainty. This approach not only maintains the integrity of the solutions but also improves their relevance in practical situations where imprecision is common. The results suggest that Gaussian elimination serves as a significant asset in the context of fuzzy systems, enabling the resolution of intricate equations that conventional methods often find challenging. The incorporation of fuzzy logic into numerical analysis expands the potential applications of linear algebra, making it pertinent across various sectors, including control systems, decision-making frameworks, and economic modeling. Future investigations should focus on further enhancing these techniques and examining additional uses of fuzzy Gaussian elimination across different fields. By persistently connecting classical methodologies with contemporary challenges, we can deepen our comprehension and proficiency in addressing uncertain and complex systems. This study contributes

to the ongoing dialogue in fuzzy systems and numerical analysis, reinforcing the idea that fundamental mathematical methods are crucial in tackling modern issues.

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